

Using Model-Based Design to Design Real-Time Video Processing Systems

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Image Processing Applications

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MathWorks Aerospace and Defense Customers Video and Image Processing Application Examples

Autonomous
Vehicles



Night Vision



Targeting



Surveillance



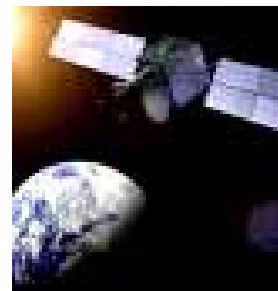
FLIR



Heads-Up Display



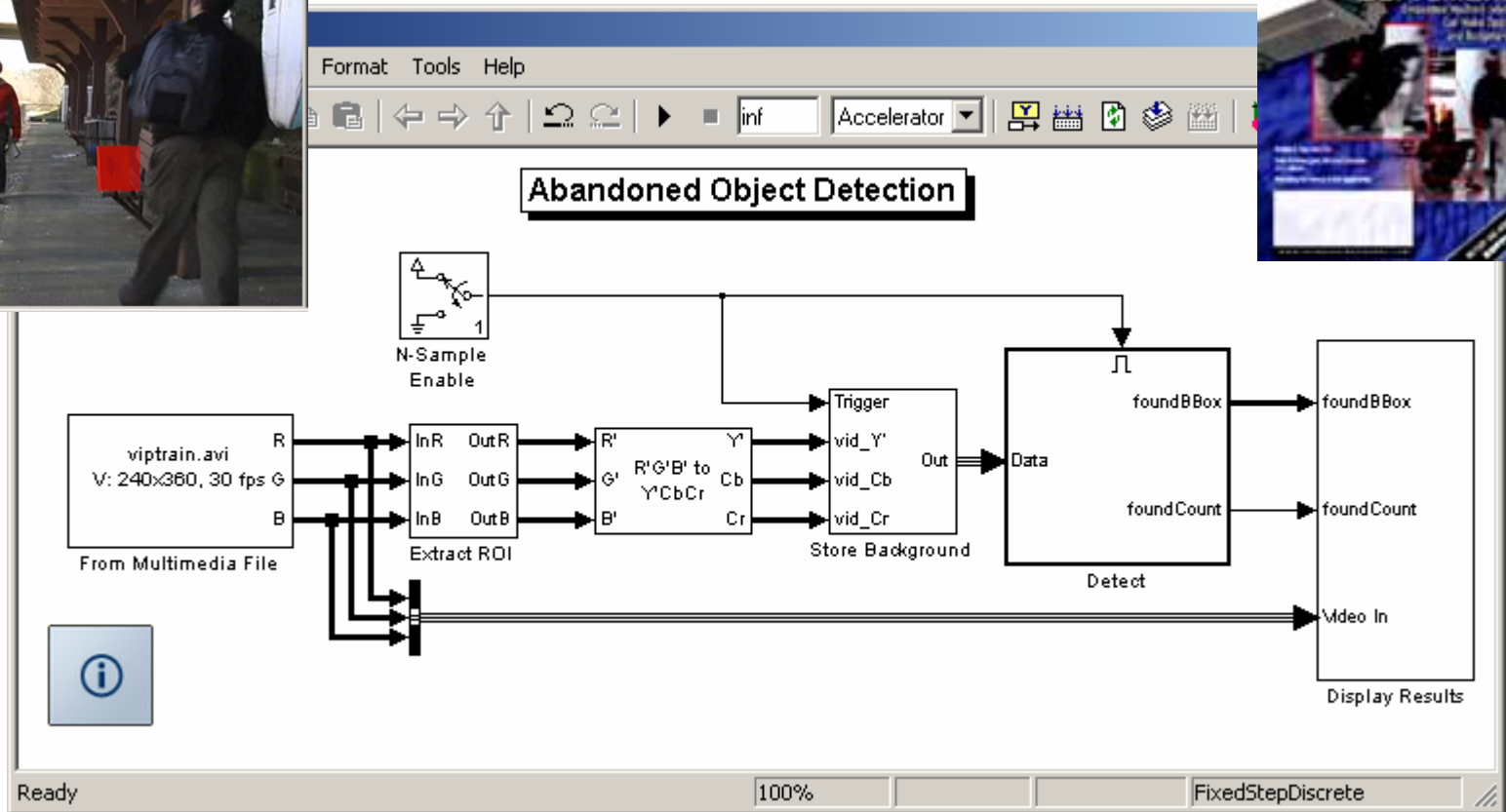
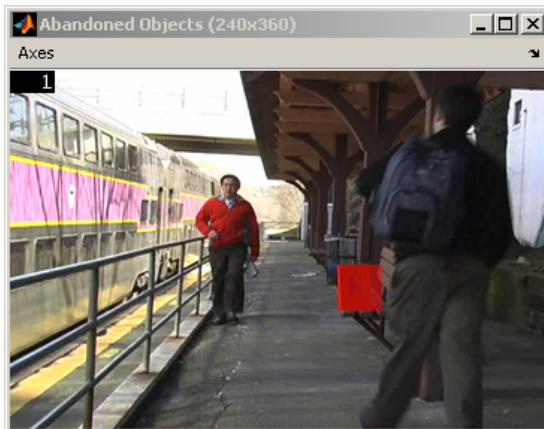
Satellite



Border Security

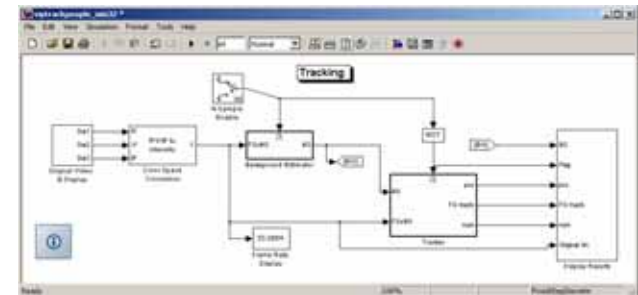


Demo: Abandoned Object Detection



Embedded Video Design Challenges

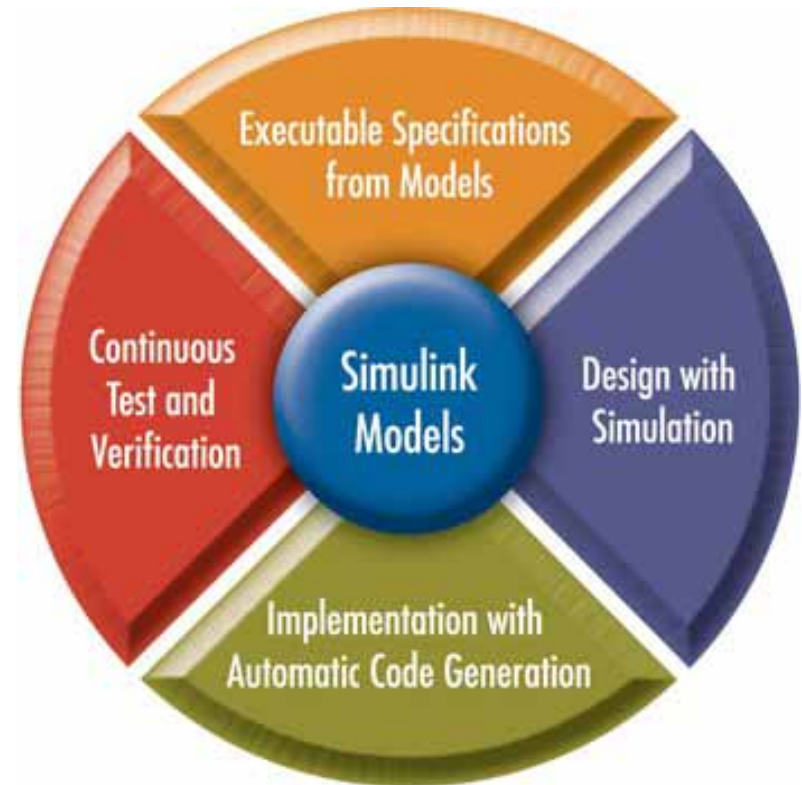
- Extreme computation demands
- Embedded system resource constraints
 - Target hardware:
 - DSP, FPGA (fixed-point)
 - Real-time requirements
- End-product focus on price, power, performance, and size
- Testing and validation of results



Model-Based Design with Simulink®

How is this useful for video?

- Implicit timing and concurrency
- Extensive algorithm library
- Fixed-point modeling
- C code generation



Video and Image Processing Blockset

Model, simulate, implement, and verify real-time video and imaging systems

- Includes more than 60 components and 100s of algorithms
- Focused on implementation of embedded systems

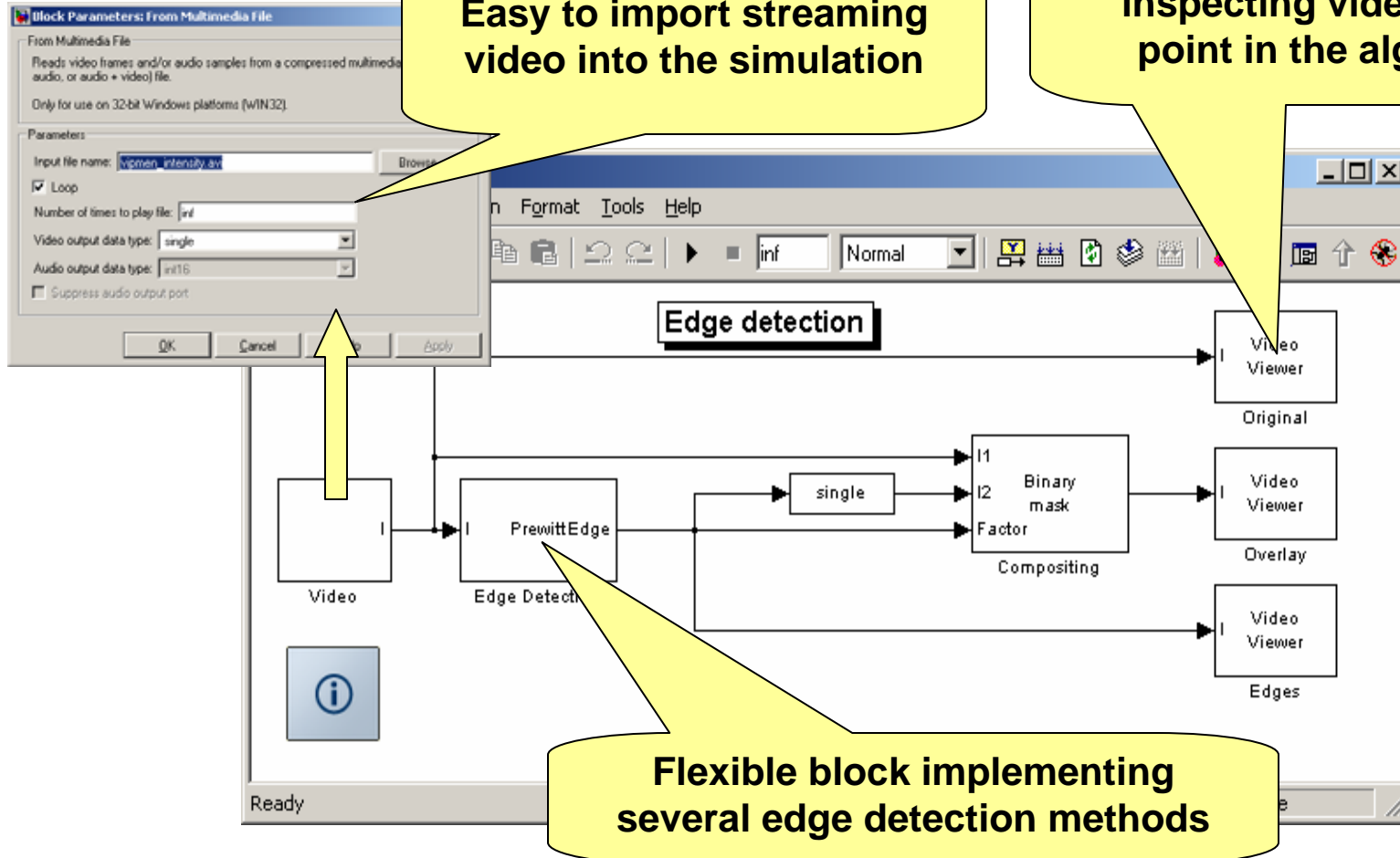


Original Video

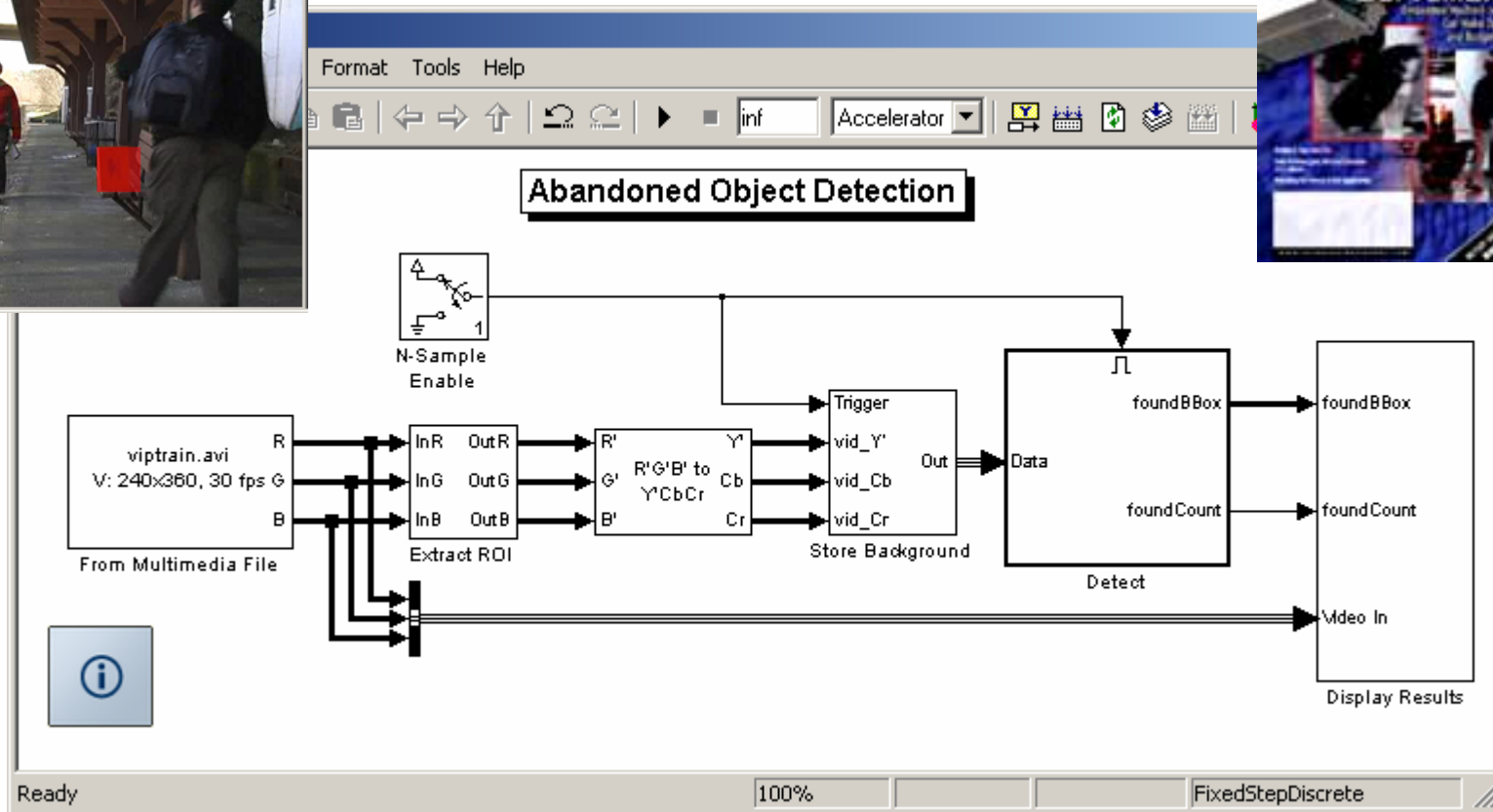
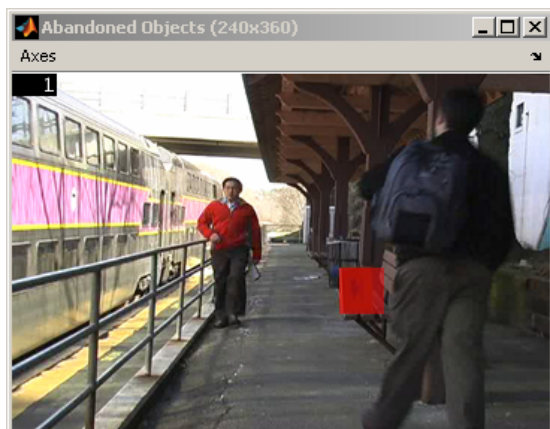


Stabilized

Demo: Edge Detection



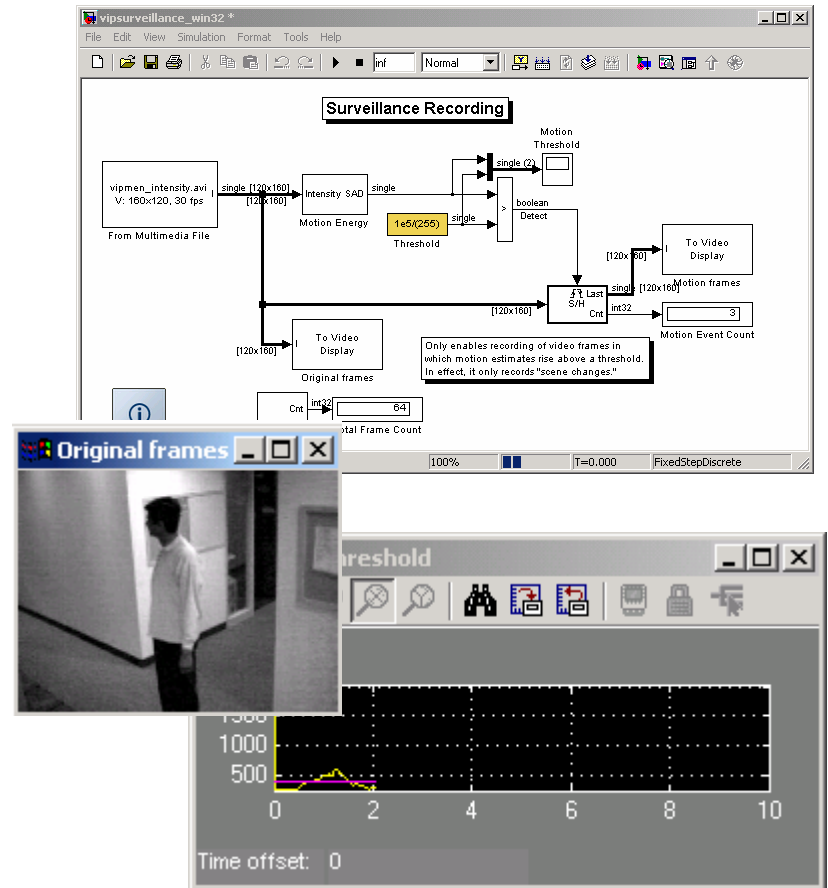
Demo: Abandoned Object Detection



Fixed-Point Modeling*

- Avoid inaccurate results due to finite word effects
- Access tools built directly into block interfaces
- Easily change parameters to model the impact of rounding, overflow, and scaling

*** Requires Simulink® Fixed Point for integer and fixed-point data types**



C-Code Generation

Breadth - Support for all embedded processors that support ANSI C

- Real-Time Workshop®
- Real-Time Workshop® Embedded Coder

Depth - Examples of processor specific enhancements

- Link for Code Composer Studio™
- Embedded Target for TI C6000™ DSP
- MathWorks Consulting
- Third-party products

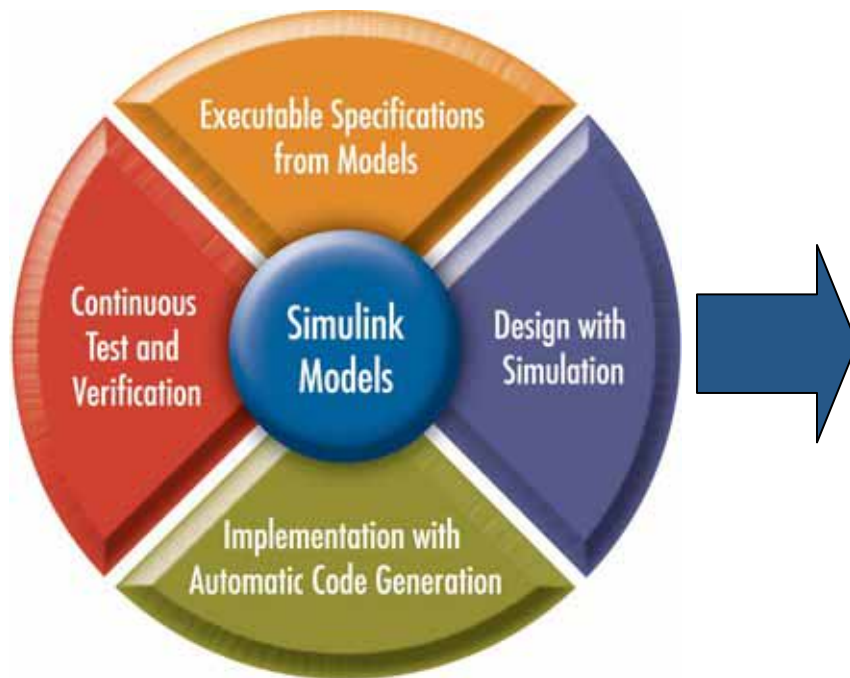


Link for Code Composer Studio™ and Embedded Target for TI C6000™ DSP

- Production code generation
 - Processor-specific, optimized code
- Project automation
 - Processor-specific, automatic
 - APIs for Code Composer Studio IDE, compiler, and linker
- Rapid prototyping
 - Target-specific and integrated
 - Simulink hardware blocks and device drivers (ADC, DAC, RTDX, daughter cards)
- Hardware Support
 - Development Boards: TI C6701 EVM, 6711 DSK, 6713 DSK, C6416DSK, and DM642 EVM
 - DSPs: TI DM64x, C64x, C62x, and C67x families



The Value of Model-Based Design



Innovation

- Rapid design iterations and “what-if” analyses

Quality

- Reduced design errors

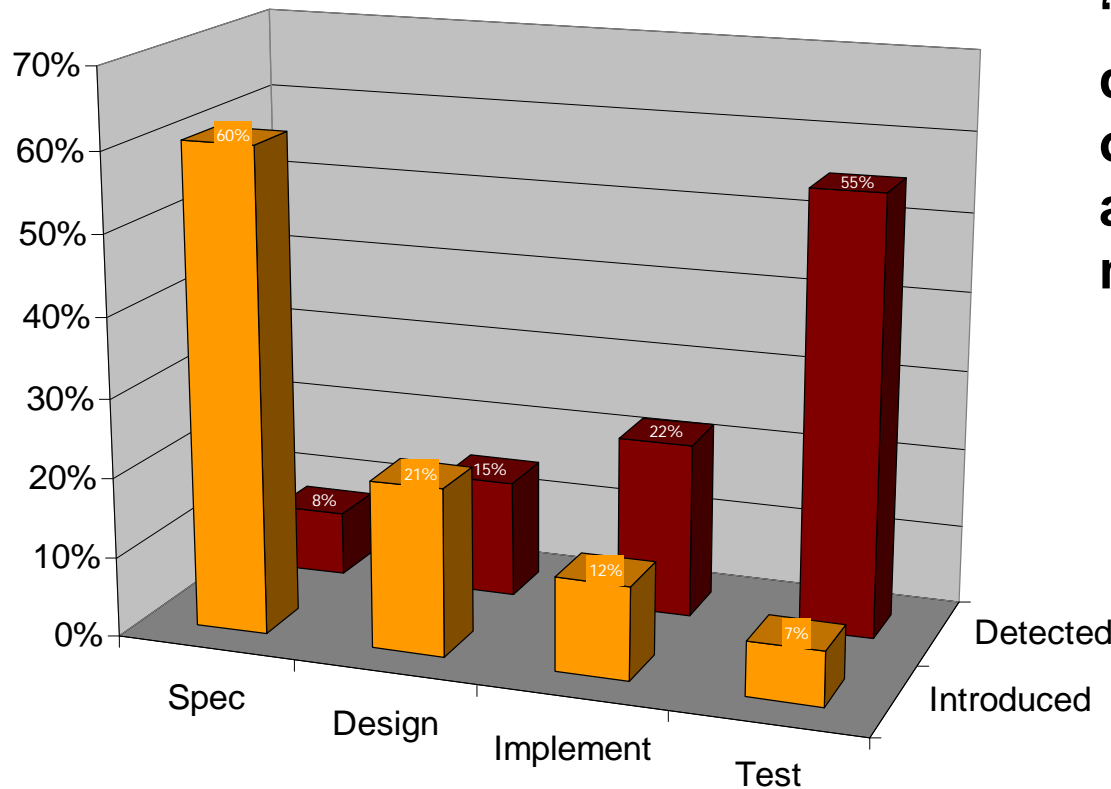
Cost

- Reduced expense from physical prototypes and re-work

Time-to-market

- Get the product right the first time

Where Errors Are Introduced ... and Detected



“Each delay in the detection and correction of a design error makes it an order of magnitude more expensive to fix.”

*Clive Maxfield and Kuhoo Goyal
 “EDA: Where Electronics Begins”
 TechBites Interactive, October 1, 2001
 ISBN: 0971406308*

Source: “Migration from Simulation to Verification with ModelSim®” by Paul Yanik.
 EDA Tech Forum, 2004 Mar 11, Newton MA

User Story: Doheny Eye Institute Enables the Blind to See with MathWorks Products



Visor Prototype

The Challenge

To develop a retinal prosthetics proof-of-concept prototype that interfaces with a permanent micro-electronic retinal implant enabling the blind to see

The Solution

Use MathWorks products for Model-Based Design to model, simulate, and generate rapid prototype of prosthetic vision system

The Results

- Completed phase II of research project ahead of schedule
- Currently in trials with patients through Doheny Eye Institute at University of Southern California

“We are working on real-time image processing with the TI DM642 processor as the target. The Video and Image Processing Blockset makes the task of creating our design and working prototypes much simpler.”

**Dr. James Weiland
Director, Intraocular
Retinal Prosthesis Lab
Doheny Institute**

Thank You



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